

# Magnet System Definition

L. Bromberg

P. Titus

MIT Plasma Science and Fusion Center

ARIES meeting

November 4-5, 2004

# Action items from ORNL meeting

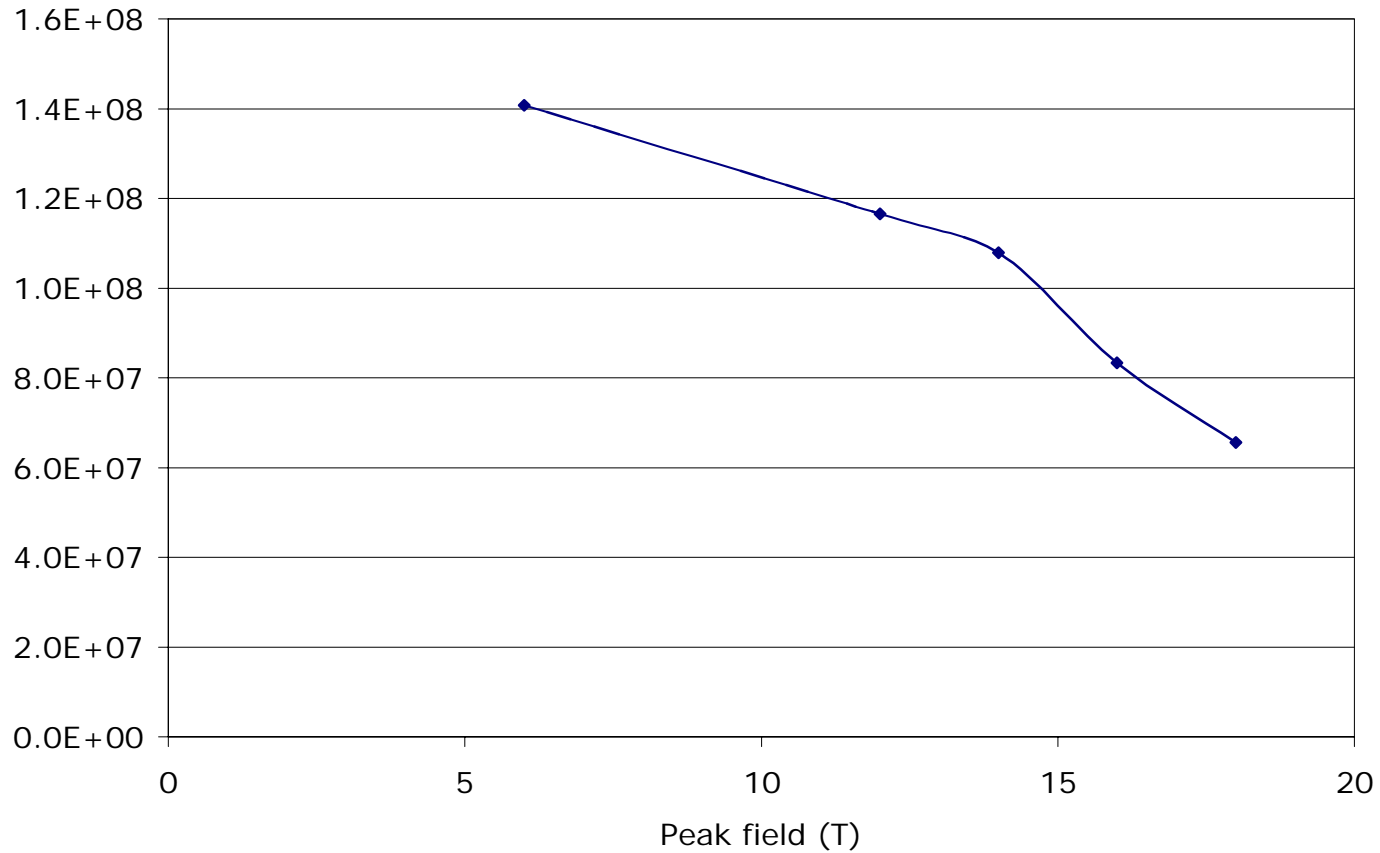
- System code:
  - Evaluate for constant fusion power/wall loading to determine the coil load line, and then decide using a conductor curve, calculate the coil-shield gap for that design.
  - System code uses square conductor cross section, which limits scaling options
    - Need additional input from PPPL
  - Repeat by varying the wall loading until the gap vanishes (or is equal to the dimension needed for assembly and maintenance).
- At MIT:
  - Need to obtain additional results for coil flux surfaces closer to the plasma, so that system code can be used to interpolate coil designs.
  - Develop coil design criteria to be used in system code (load line) to determine smallest coil.
  - Comparison poloidal cases vs a toroidal case

# System code magnet module

- Superconductor current density
  - Load line
- Stellarator calculations limited database
  - Need additional cases from PPPL
- Structure
  - Bending vs hoop
  - Implications of deformations on magnet structure

# SC design “load line”

Low TC like SC



# Magnet issues

- Meeting SC load line by decreasing cross section of magnet and varying the shape-factor  $k$  of the winding pack
  - make the superconductor as wide in the toroidal direction as possible, and decrease the thickness of the conductor to meet SC load line

# Magnet Structure

- An algorithm has been provided for evaluating the required structure, on the basis of stress constrain
- Slight differences on the thickness of the structure cross section on the outboard side remains between the drawings/assumptions and the algorithm.
- It is relevant because the outer region of the magnet determines to 0<sup>th</sup> order the weight of the magnets and cost of the structure.
- As opposed to tokamaks, the space in the inboard region is not critical

# Wound conductor

- In the case of wound conductor, means of transferring loads to structure are needed
- In NCSX, ribs are placed within conductor
- For ARIES-Stellerator, large loads required stiff ribs.
- Distance between coils need to be adjusted for non-radial load transfer
- Need to determine loads to determine thickness of reinforcement ribs





# Coil structure and costing

- Case analyzed is 8.1.31



Bo	T	5.80487436
Ro	m	7.20497912
Plasma ASPECT ratio		4.5
INBOARD gap/blanket/shield thicknes	m	1.08448001
OUTBOARD gap/blanket/shield/gap	m	1.07005693
Coil height	m	15
Outer radius of inner leg, Rin		6.69
Inner radius of outer leg, Rout		13.29
A		2.50E+09
S1		1.42E+08
S2		5.71E+07
sigma membrane allowable	Pa	6.00E+08
sigma bending allowable		9.00E+08
Total thickness of inner leg	m	0.55
Thickness of inner leg (hoop compression)	m	0.31
Thickness of inner leg (tension)	m	0.24
Thickness of outer leg, tout	m	0.10
Thickness of top/bottom	m	0.35

# Thickness of outer leg

- For 8.1.31 case, required thickness of outer leg is 0.1 m
- However, structure in the outside looks like Swiss cheese due to presence of large ports
- Assuming that ports take  $\sim 30\%$  of cross section, thickness of coil needs to increase by a factor of 2
- Numbers provided for neutronics/drawings include this effect
- However, for costing assume the thin homogeneous cross section

# Costing of magnet structure

Volume:

large ellipsoid	m <sup>3</sup>	5956
Small ellipsoid	m <sup>3</sup>	4881
Total	m <sup>3</sup>	1075

Weight	ktonnes	8.6
Assume \$50/kg		51
cost of structure	M\$	438

# Deformation

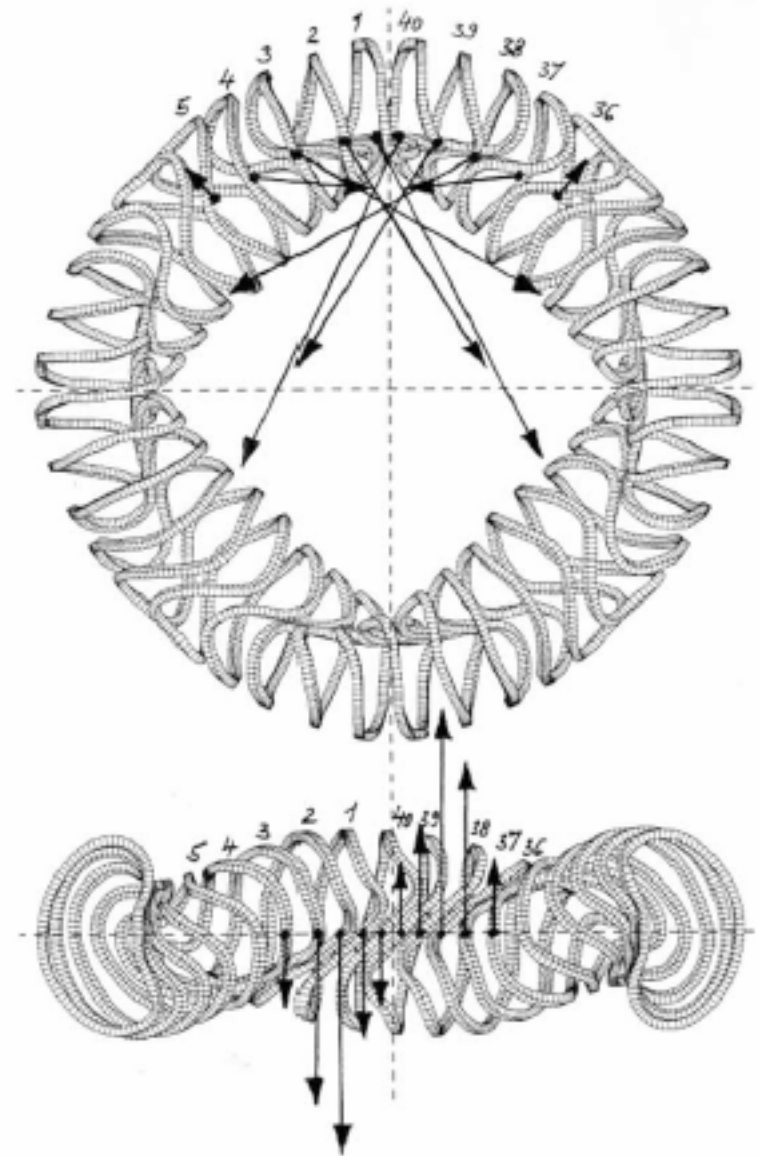
- As opposed to axisymmetric configurations, deformation of coils results in substantial field errors
- Local deformation can be dealt by designing locally strengthened structures
- Global deformations can be incorporated in the design or can be supported

## Simplified impact of forces on deformations

- Coils in stellerators have forces that:
  - Tend to inflate the coils
  - Straighten the kink
  - Net radially inward force
- Deformation of the coils follow (in an integrated sense) these loads

# Load behavior in Stellerator geometries

HSR4/18: Net coil forces.



Improved support concept for the Helias reactor coil system

E. Harmeyer\*, J. Kiblinger

Max-Planck-Institut für Plasmaphysik, EURATOM-Association, D-17491 Greifswald, Germany

Fig. 1. Net coil forces of the HSR4/18 configuration.



# Deformation

- Coil case is insufficient to provide sufficient stiffness to coils to prevent large deformations
- If exclusively toroidal fields, coil wants to take D-shape, resulting in very tall coils
- Shell structure is much more efficient

# Coil global deformations

- For structural efficiency
  - Deformation  $\sim 0.2\%$  strain (determined by the superconductor)
  - Assume typical dimension  $\sim 12$  m
  - Maximum global deformation  $\sim 2$  cm
  - Non-symmetries can place substantial strains that need to be balanced by rib-like structure
- Design coil so that when loaded conductor is at desired location
  - Global deformation does not add to constrain
  - Local deformation needs to be handled by point design

# Conductor support

- As opposed to NCSX, there are no large thermal differentials (from conductor heating)
- Conductor (in the case of wound) can be impregnated into structure, simplifying load transfer from conductor to structure
- In the case of HTS material, conductor is directly supported by structure

# Future work

- Need to verify that the maximum field as a function of coil-shape  $k$  for a set of coils
- Need to prepare for calculations of loads and structure for a case
- Determination of structure deformation from loads, including openings